

Hyper-Star Graph: A New Interconnection

the network cost, defined by degree \mathcal{E} diameter, is introduced as a measure for interconnection networks [4, 5, 7].

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Theorem 1. *A hyper-star graph $HS(n; k)$ is isomorphic to a hyper-star graph $HS_{\mathbb{E}}(n; n_j, k)$.*

Since $HS(n; k)$ is isomorphic to $HS(n; n_j, k)$, throughout the paper, we assume that $k \leq \frac{n}{2}$ unless explicitly mention.

2.2 Connectivity

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For two nodes $S = s_1 s_2 \dots s_n$ and $D = d_1 d_2 \dots d_n$, denote by $R = r_1 r_2 \dots r_n$ the bit string obtained by applying *Exclusive-OR* operation between S and D . We use \oplus to represent the Exclusive-OR operator. Each i -dimensional edge,

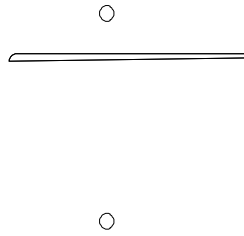


Fig. 3. $FHS(4;2)$ graph

the hypercube and its other variations such as folded hypercube[6], multiply-twisted cube[4], and hierarchical cubic networks(HCN) [8]. Basic parameters such as the size, degree, diameter and the network cost of folded hyper-star graph, hypercube and its other variations are shown in Table 1.

Table 1. Network cost of the hypercube and its variations

Network Model

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Shortest_path_2( $S; D; P_s$ )  
begin  
   $k = 0$ ;  
  if ( $S = D$ ) then  
    return  $P_s$ ;  
  obtain  $R = r_1 r_2 \dots r_i \dots r_{2n}$ , where  $r$ 
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